



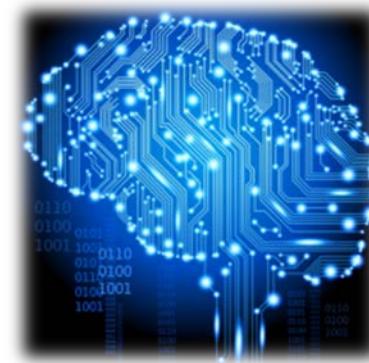
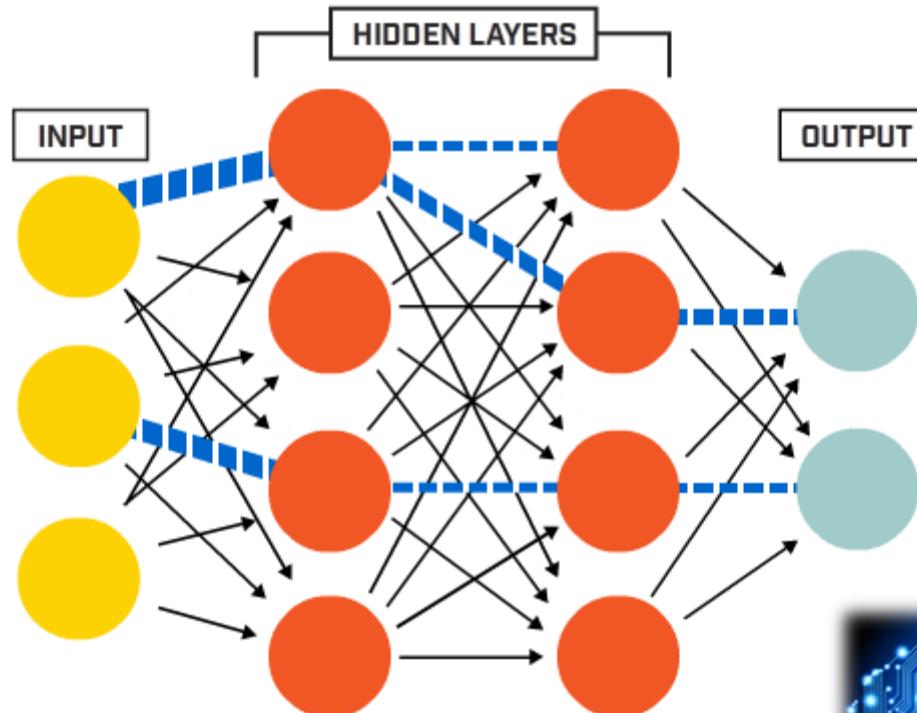
## Mastering Automated Visual Inspection

### *Future Trends in Automated Inspection*

- What is deep Learning ?
- How deep Learning will transform VI ?
- Key Milestones last decade
- 1st proof of concept with cracks and particles



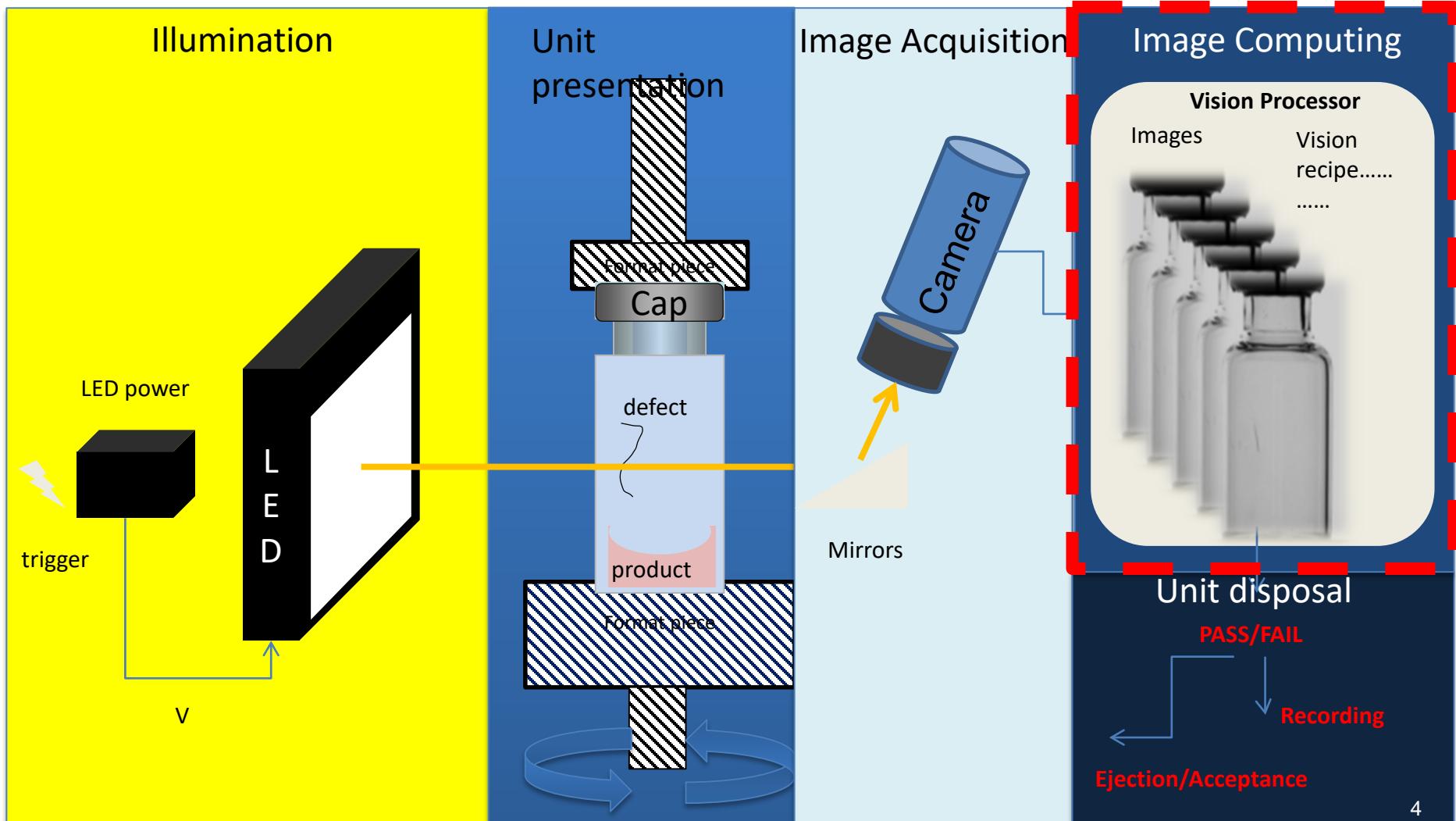
# Deep Learning Vision



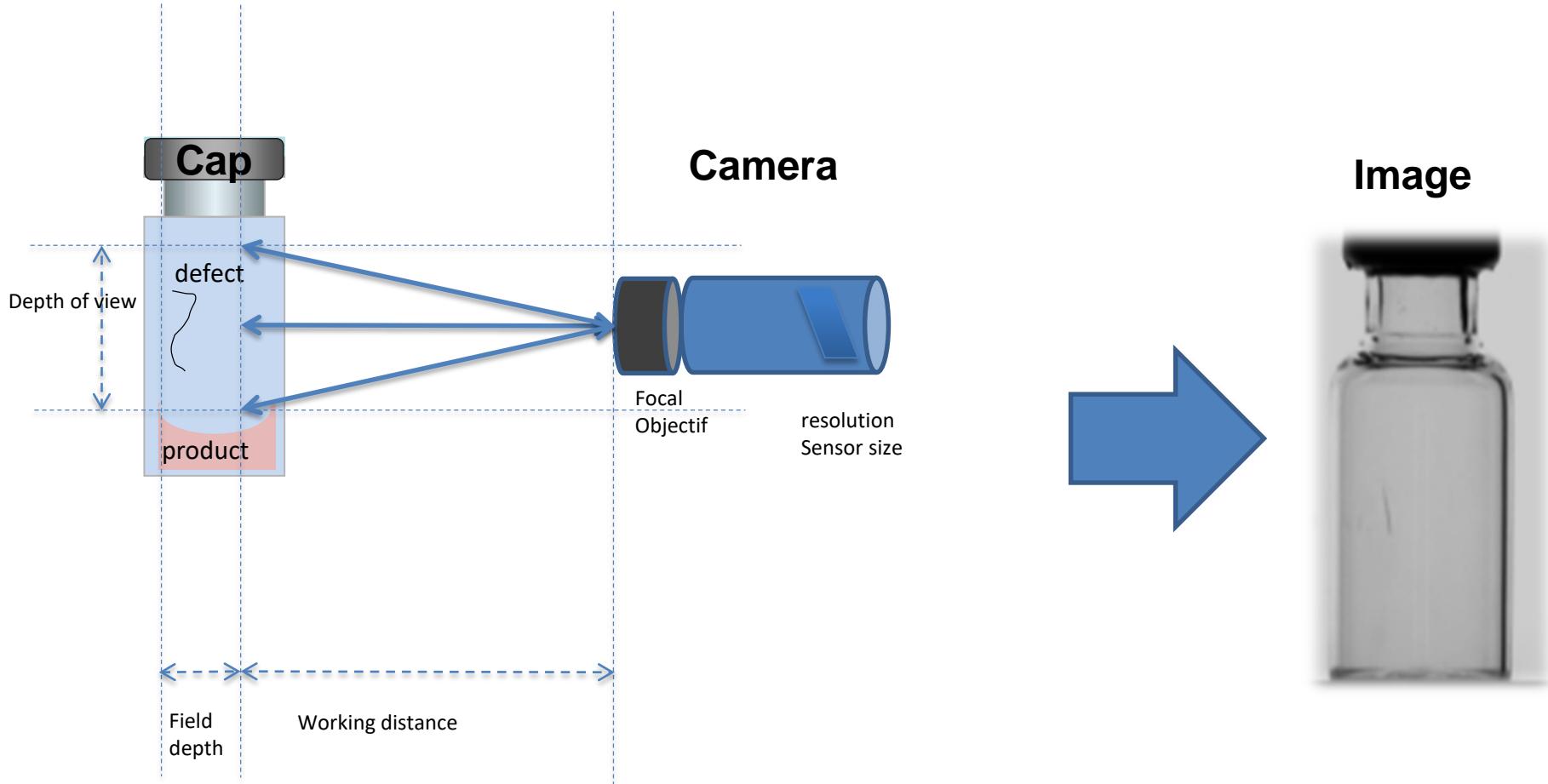
**Objective:** Presentation of current trends in AVI  
and computer vision

1. Main function blocks of AVI
2. What can « see » a machine?
3. Historic milestones
4. Comparison Man/machine
5. How is working « deep learning » ?
6. Some practical demos

# Deep Learning will impact Image computing + Defect Classification

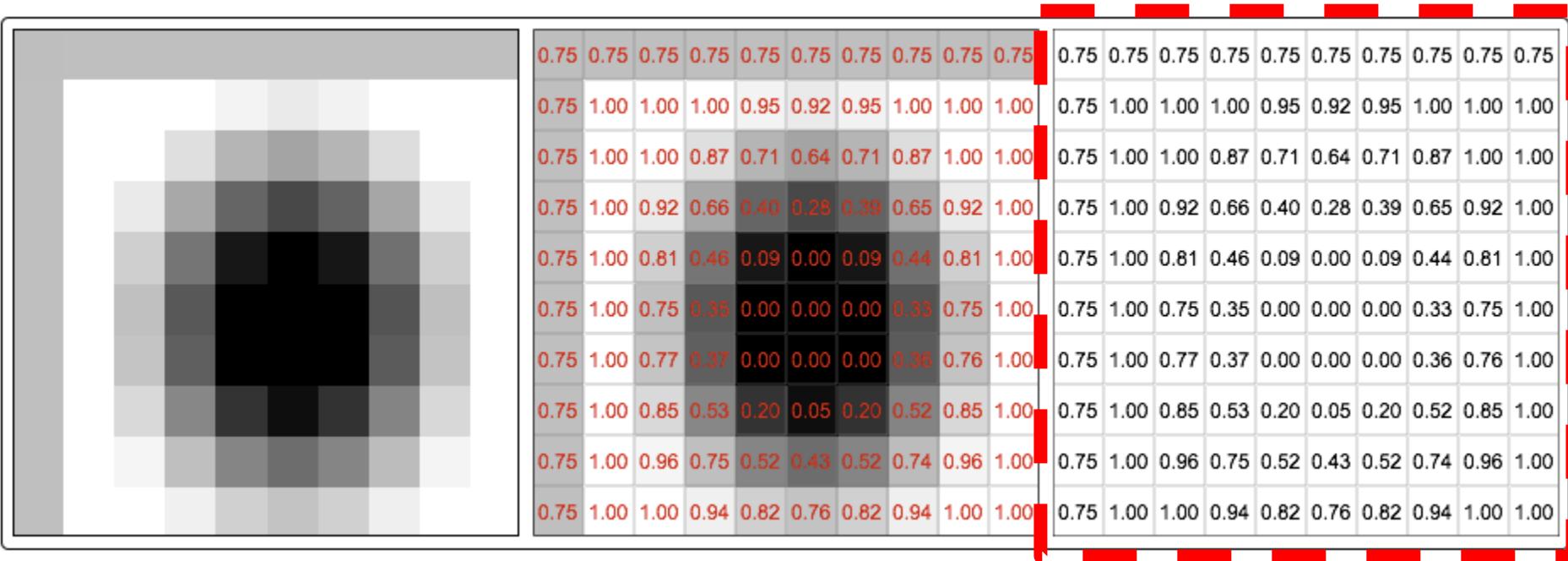


# Image Acquisition principle will remain the same



## Theory 2: Introduction to technical principles of automated inspection machines

# What a machine really sees, what is DIP?

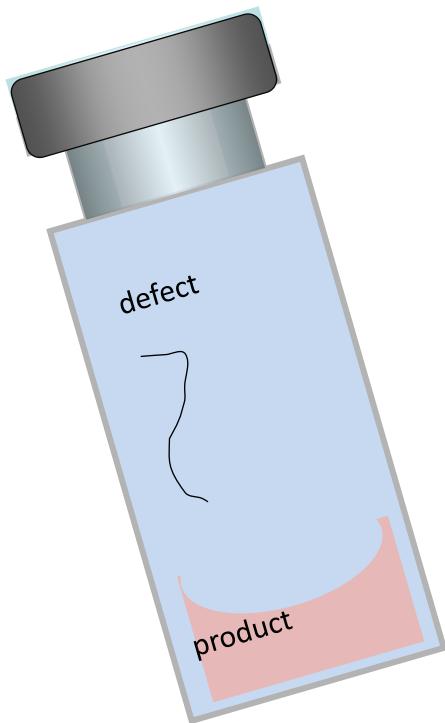


1 particle

Image with grey level...

Digital Image = matrix grid of  
figures ☺

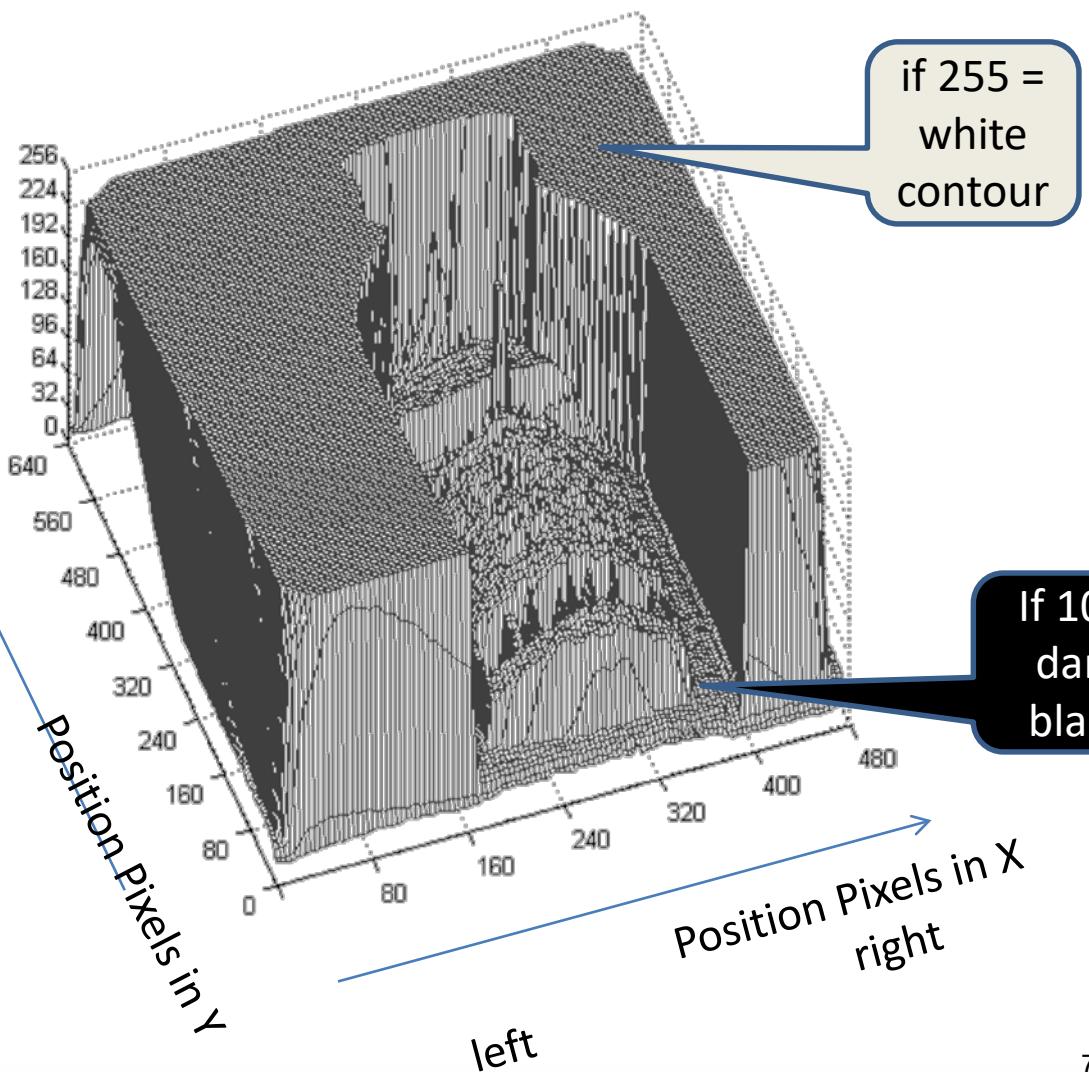
# What a machine really sees, what is a Digital image?

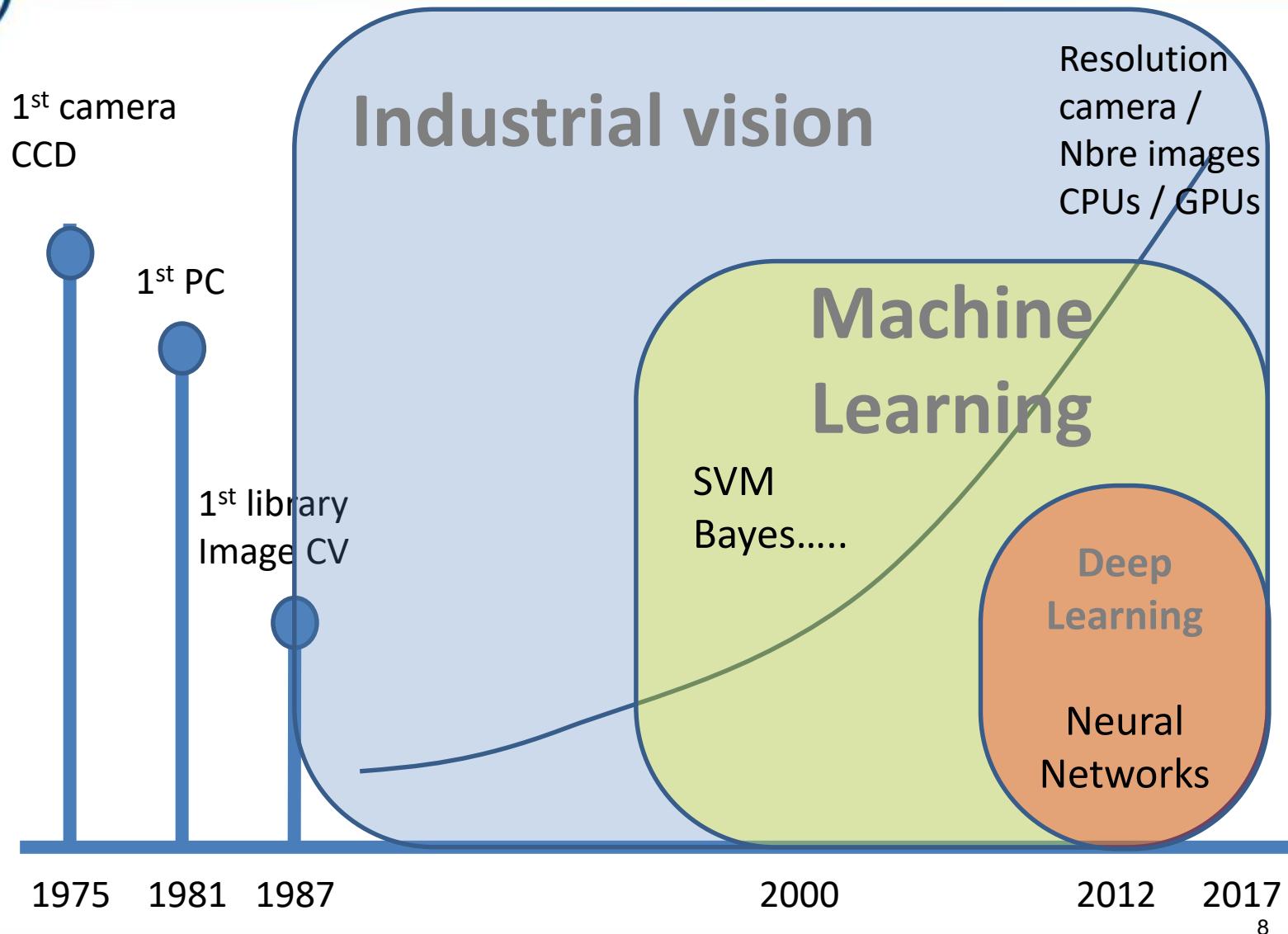


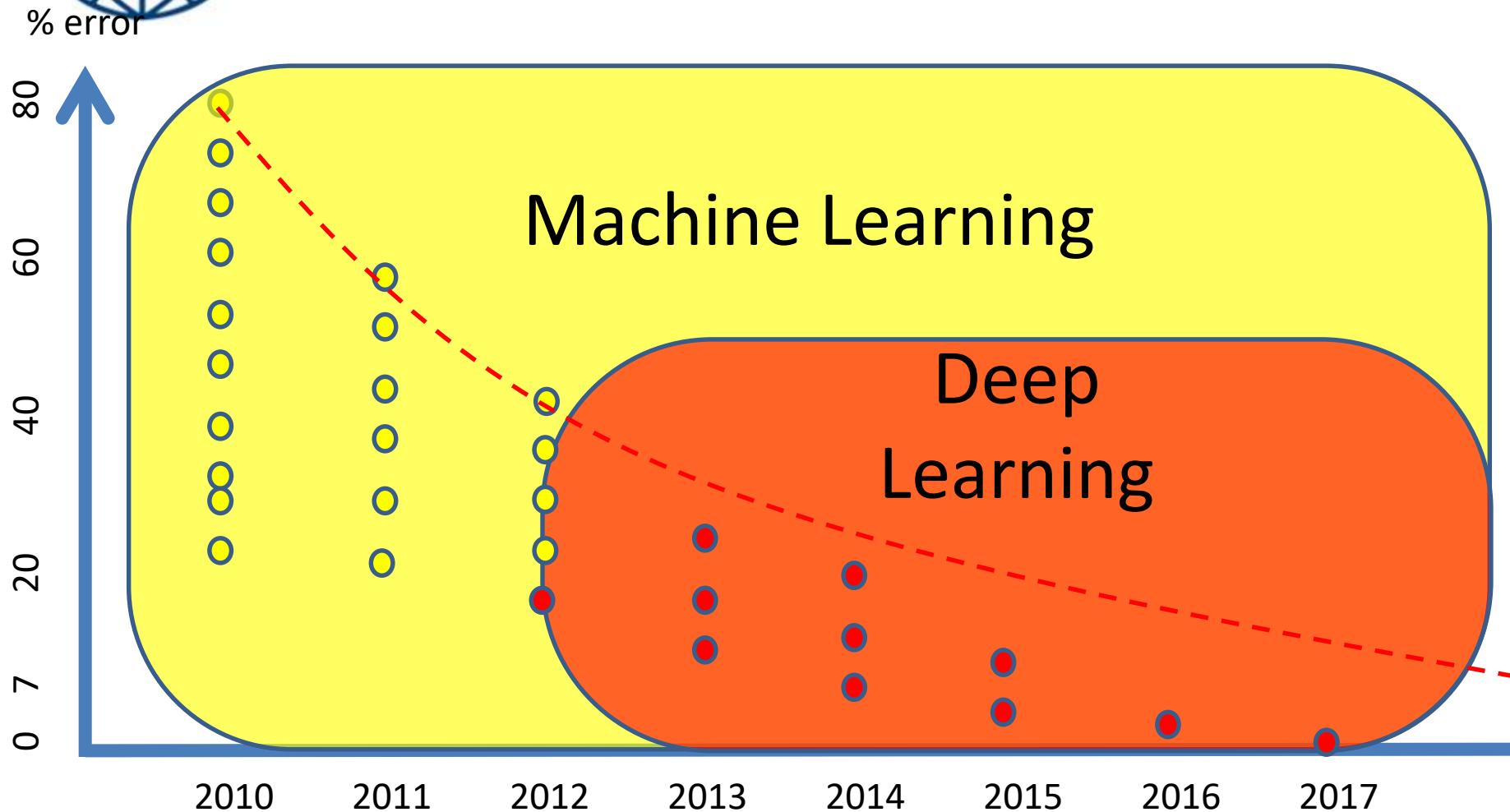
Grey level 8bits  
255=white

0=black

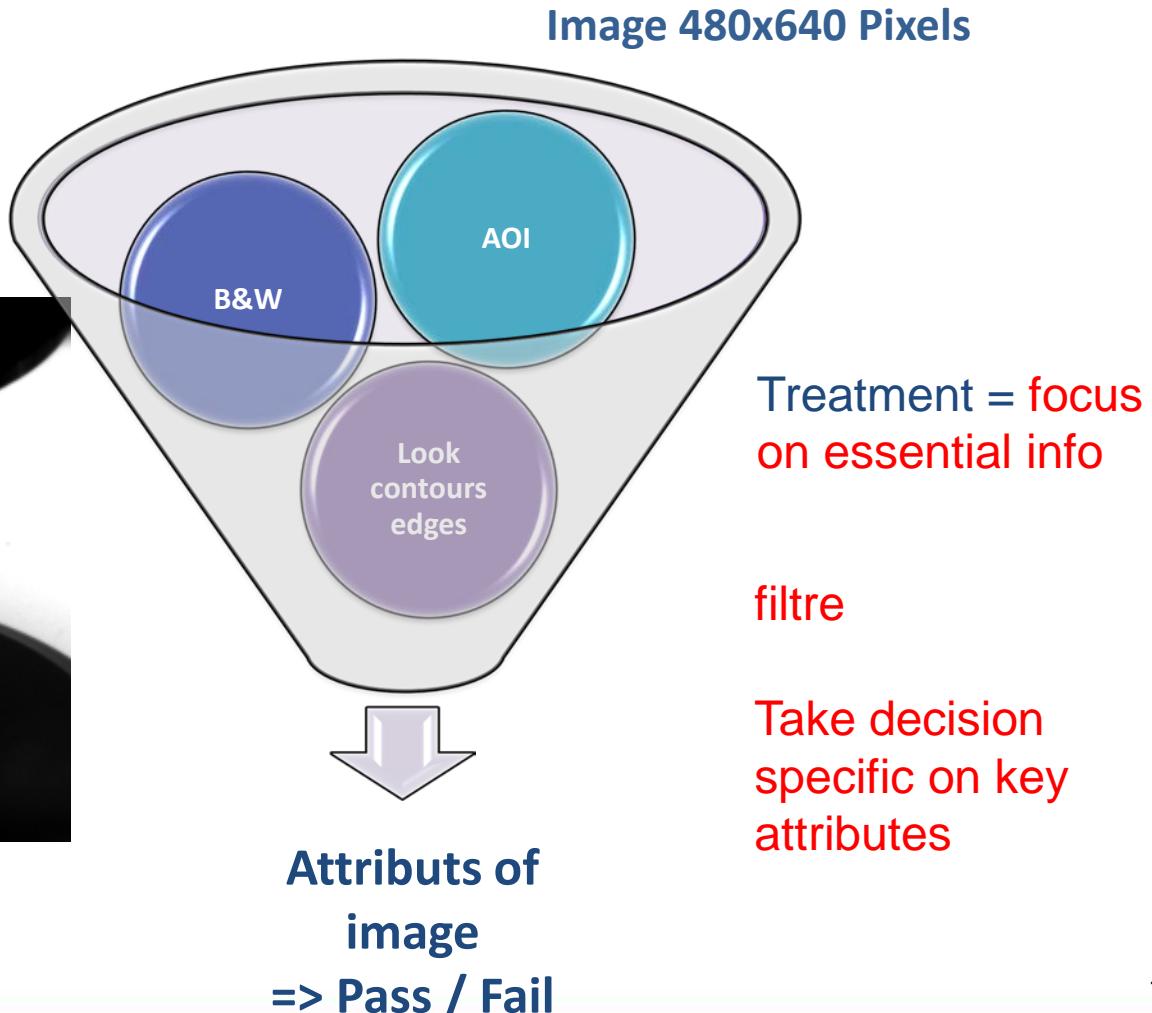
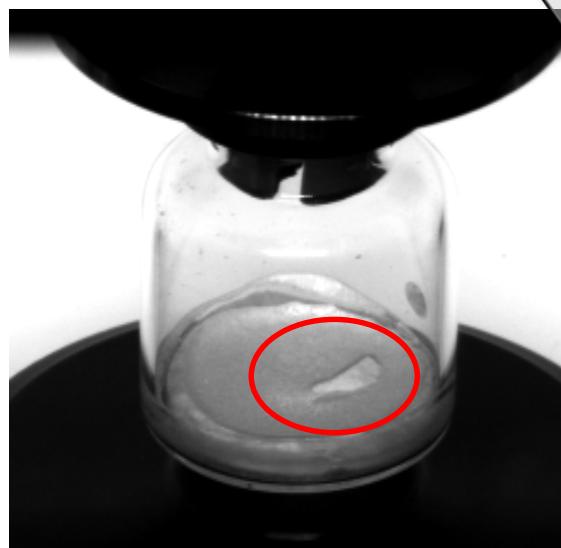
Top  
bottom

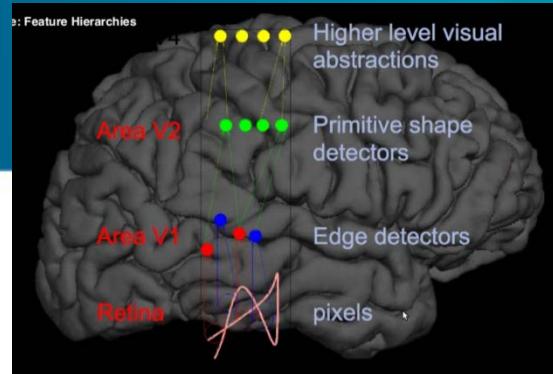






# Why ? Too much useless infos in images

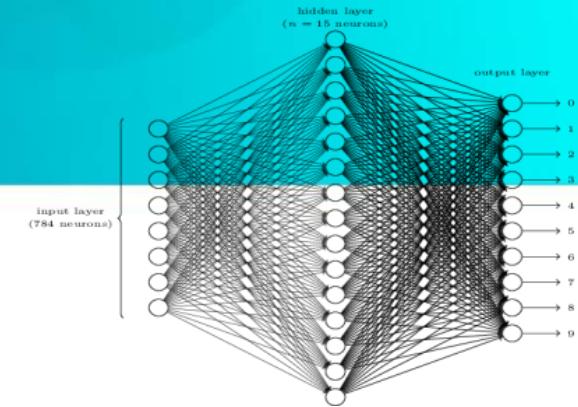




## HUMAN MVI

- ✓ 1 real object object that was teached to the machine = supervised learning
- ✓ Observation; concentration / light/ fatigue....
- ✓ Cones in retina activated
- ✓ Image projected in V1 area of brain for detection angles/ edges /contours
- ✓ Area V2 of brain to detect gross forms/shapes
- ✓ Area V4 -V5 for forms more abstract
- ✓ Activation memory area

→ Object Identification +classification



## DEEP LEARNING

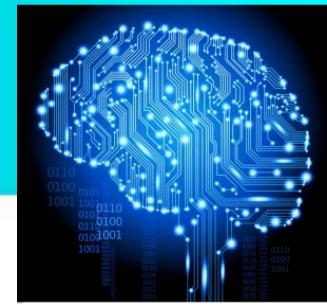
- ✓ 1 real object that was taught to the machine = supervised learning
- ✓ Image camera capture
- ✓ Presentation of image in 1st layer of neuron = nbre pixels
- ✓ Each part of image is sent to other layers of neuron that are interconnected, adjustment of coefficients to match elements as best
- ✓ Last neuron layer to classify object

→ Object Identification=classification



## Industrial vision

- ✓ Ajustement light
  - + optic + image
- ✓ Image Capture
  - Images confoirming units (kits)
  - + defect images (kits)
  - + identification defects (logbooks)
- ✓ Preparation of image treatment for each camera
  - click and drag software
  - opened computing or hard coding
- Optimization processing time
- ✓ Adjustement on images / auto ajust.
- ✓ Evaluation on machine
- ✓ Validation (PQ)
- ✓ Go Live to production



## Deep Learning

- ✓ Ajustement light
  - + optic + image
- ✓ Image Capture
  - Images confoirming units (kits)
  - + defect images (kits)
  - + identification defects (logbooks)
- ✓ Construction of 2 data bases of image:
- ✓ learning (training\_set)
- ✓ Evaluation (Prediction\_set)
- ✓ Programmation neural network
- ✓ Evaluation & adjustements
- ✓ Optimisation processing time
- ✓ Validation (PQ)
- ✓ Go live to production

# Lets give it a try?



## 1 Transversal Learning

440 images of syringes (Conform/Crack/Particle)

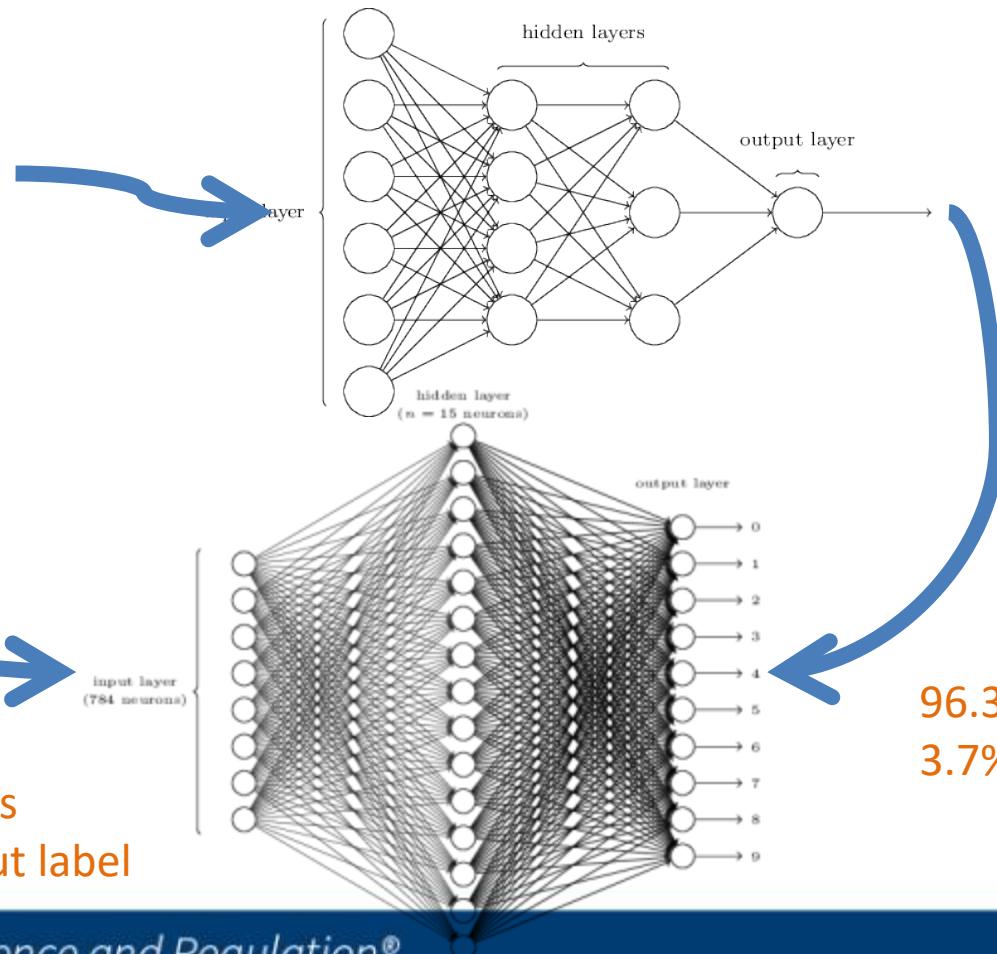
+ corresponding labels

neural network pretrained (Lenet.org)



## 2 Evaluation

Submit new images  
never show without label



96.3% of labels found OK  
3.7% « error » or just

# What you need ?

✓ 1 PC Linux



✓ Python + OpenCV



✓ Scikit-learn

✓ TensorFlow + Keras

## Deep Learning

✓ Some images

