

- Exercise 2: Principle Basic Image Processing

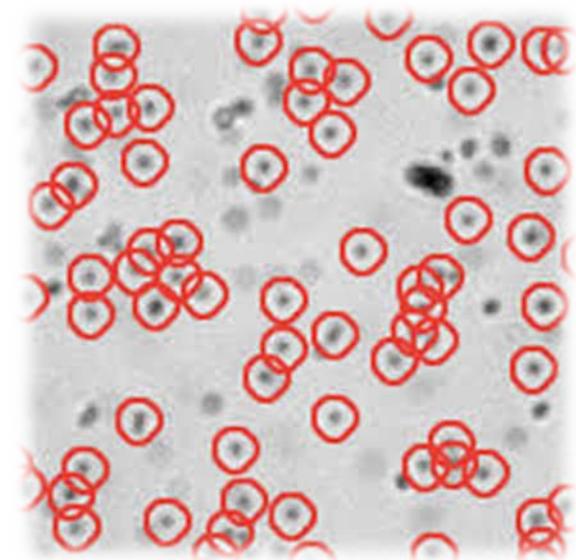


- Introduction to concept of computer vision using OpenCV Linux computation
- Practical exercise with defect detection (in partnership with ext company)

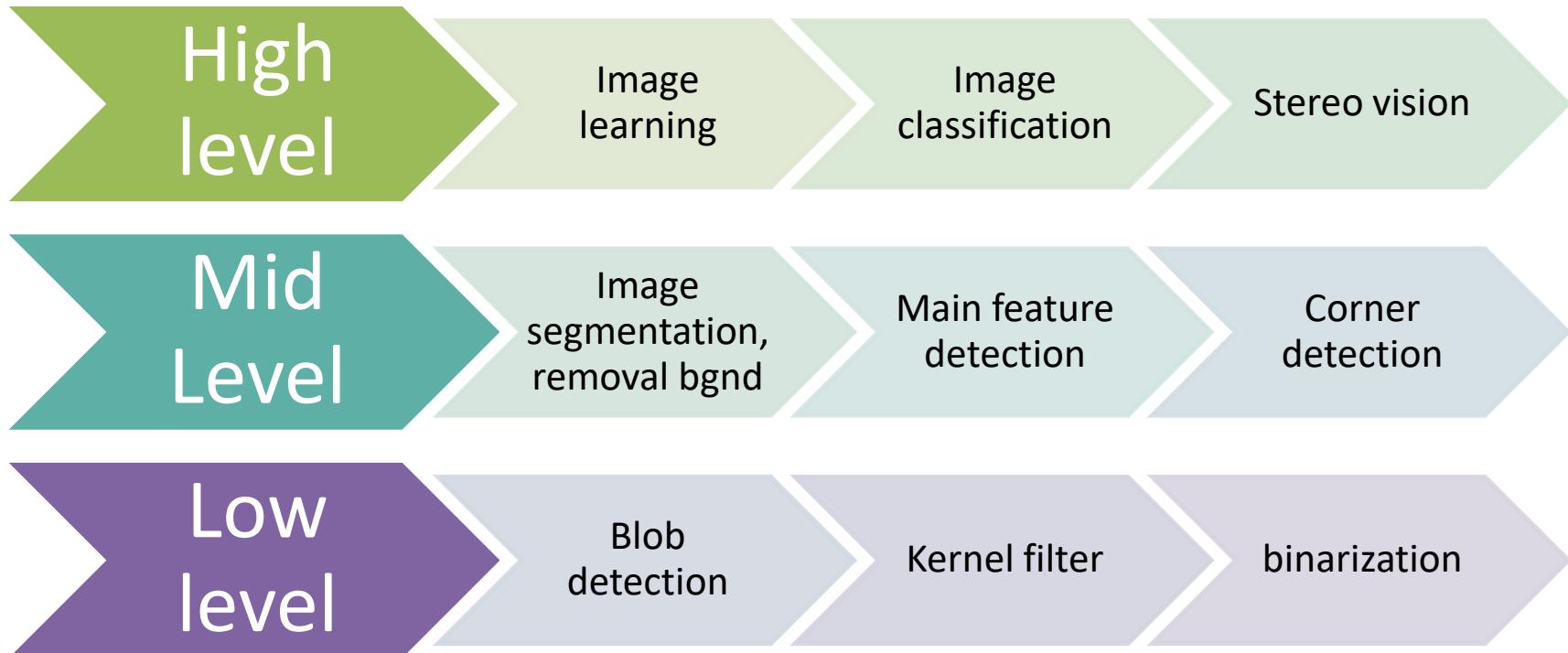
- Basic computer vision introduction
- Principle : demo using OpenCV Linux
- Topics to cover the entire flow of defect detection :
- Image binarization
- Image centering
- Image filtering in 2D (sharpen/morphogy)
- Image feature extraction (blob / corner / contour)
- Image feature attributes (shape, position, number, color....)
- Image masking
- .....
- To Higher level image classification



- Basic computer vision introduction
- Principle : demo using OpenCV Linux



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# Image processing Treatment

## Convolution filters introduction

Input image

		$a_1$	$a_2$	$a_3$				
		$a_4$	$a_5$	$a_6$				
		$a_7$	$a_8$	$a_9$				

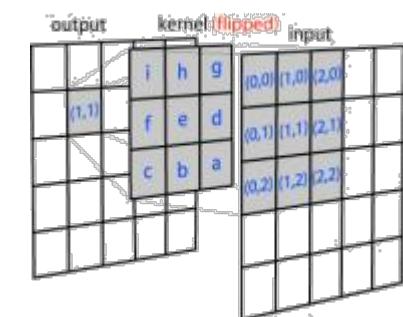
Kernel grid

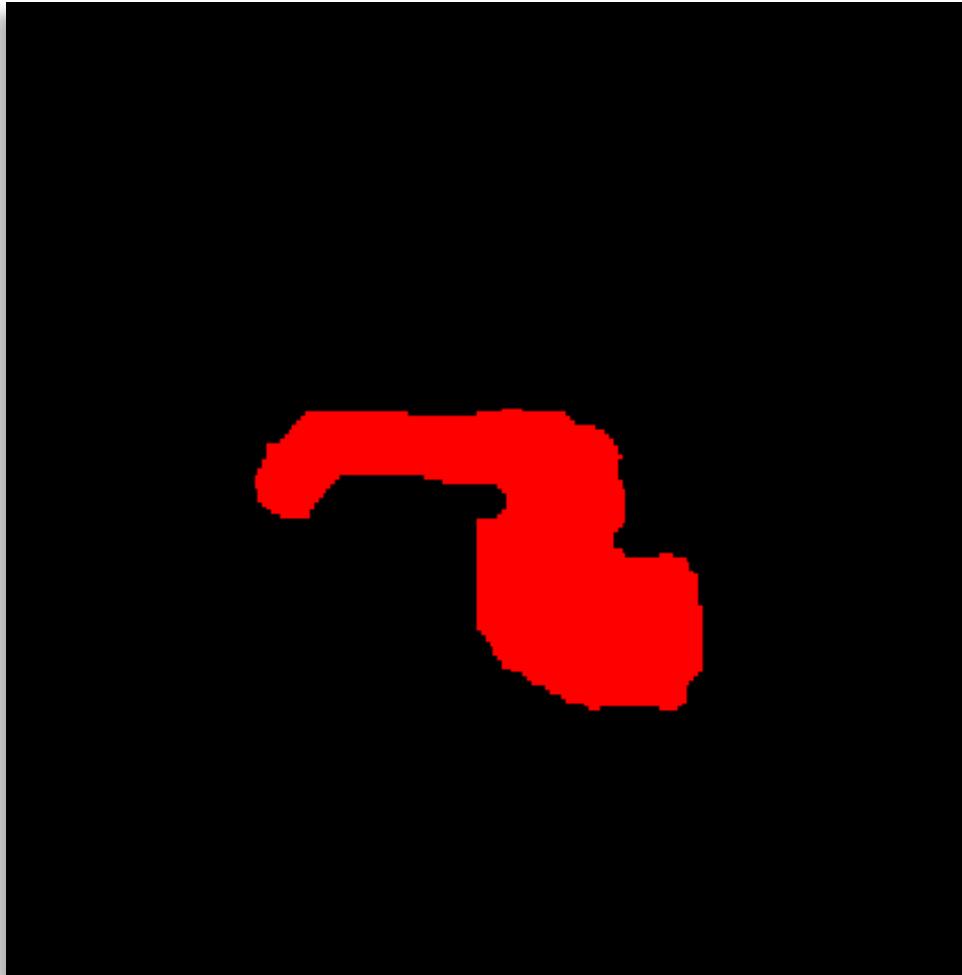
$b_1$	$b_2$	$b_3$
$b_4$	$b_5$	$b_6$
$b_7$	$b_8$	$b_9$

Output image

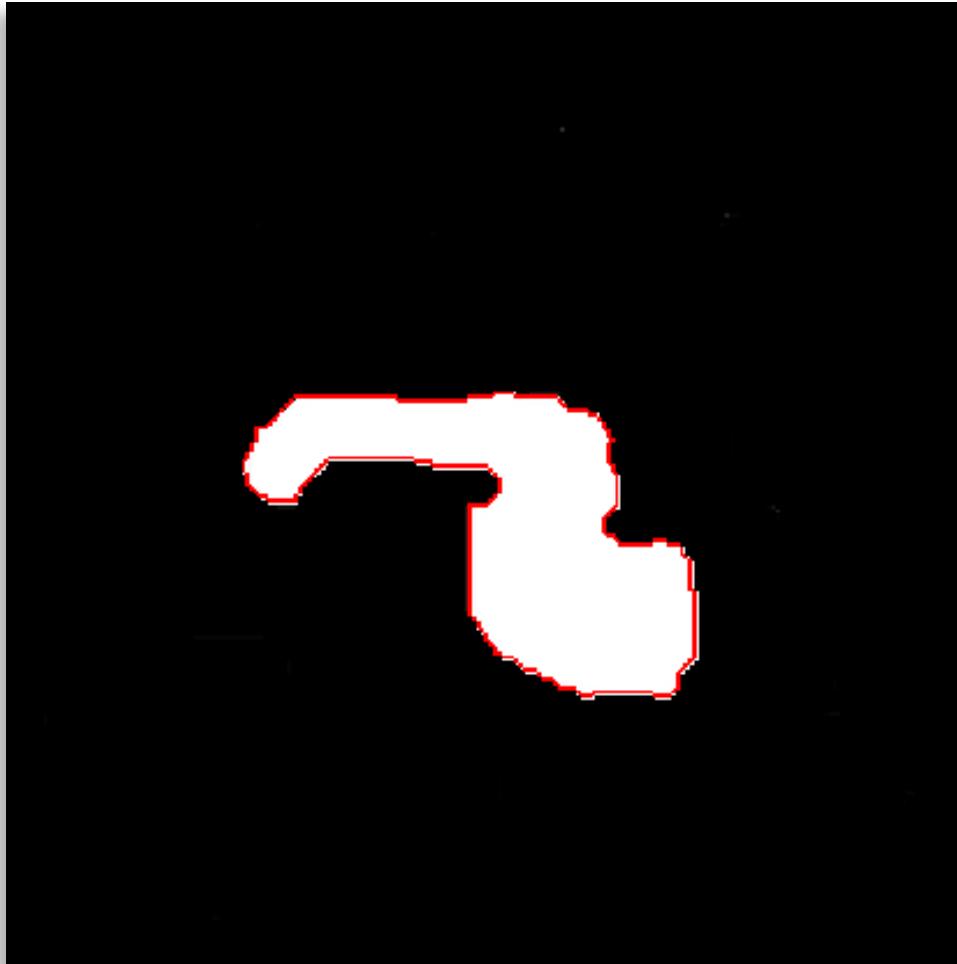
		$a_1$	$a_2$	$a_3$				
		$a_4$	$g_5$	$a_6$				
		$a_7$	$a_8$	$a_9$				

$$G_5 = (a_1 \times b_1) + (a_2 \times b_2) + \dots + (a_9 \times b_9)$$

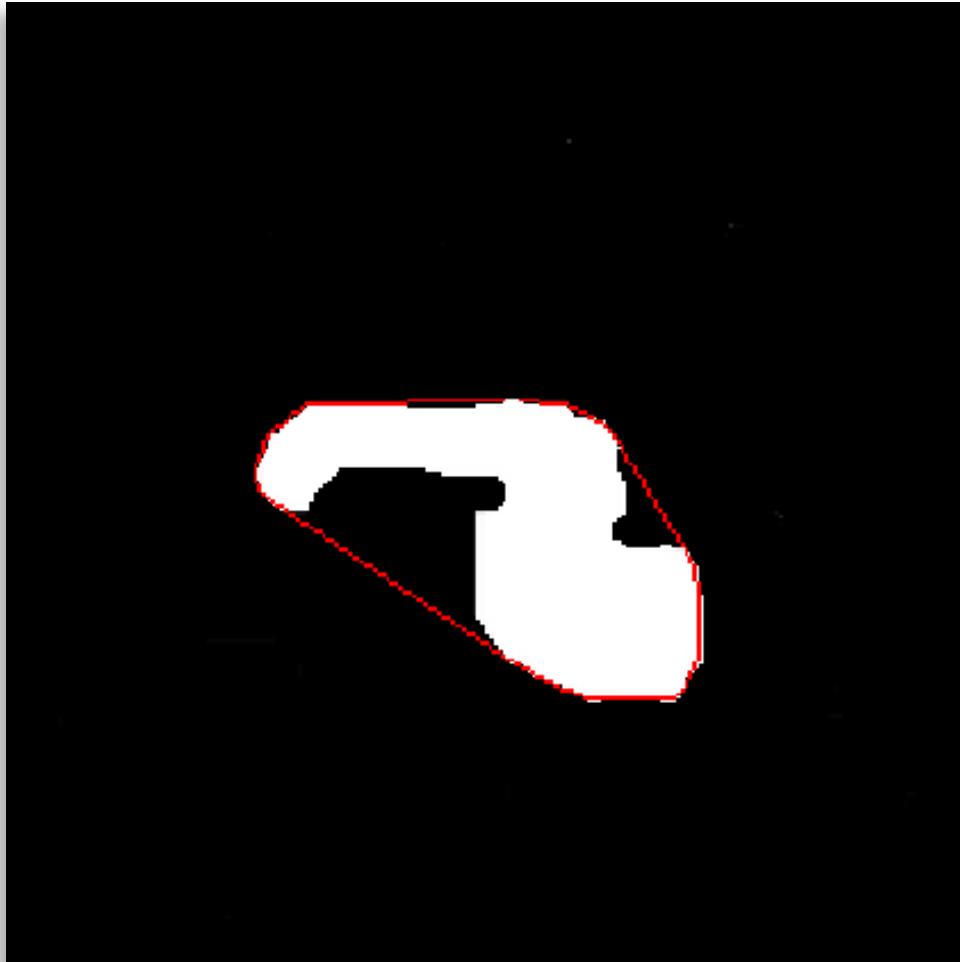




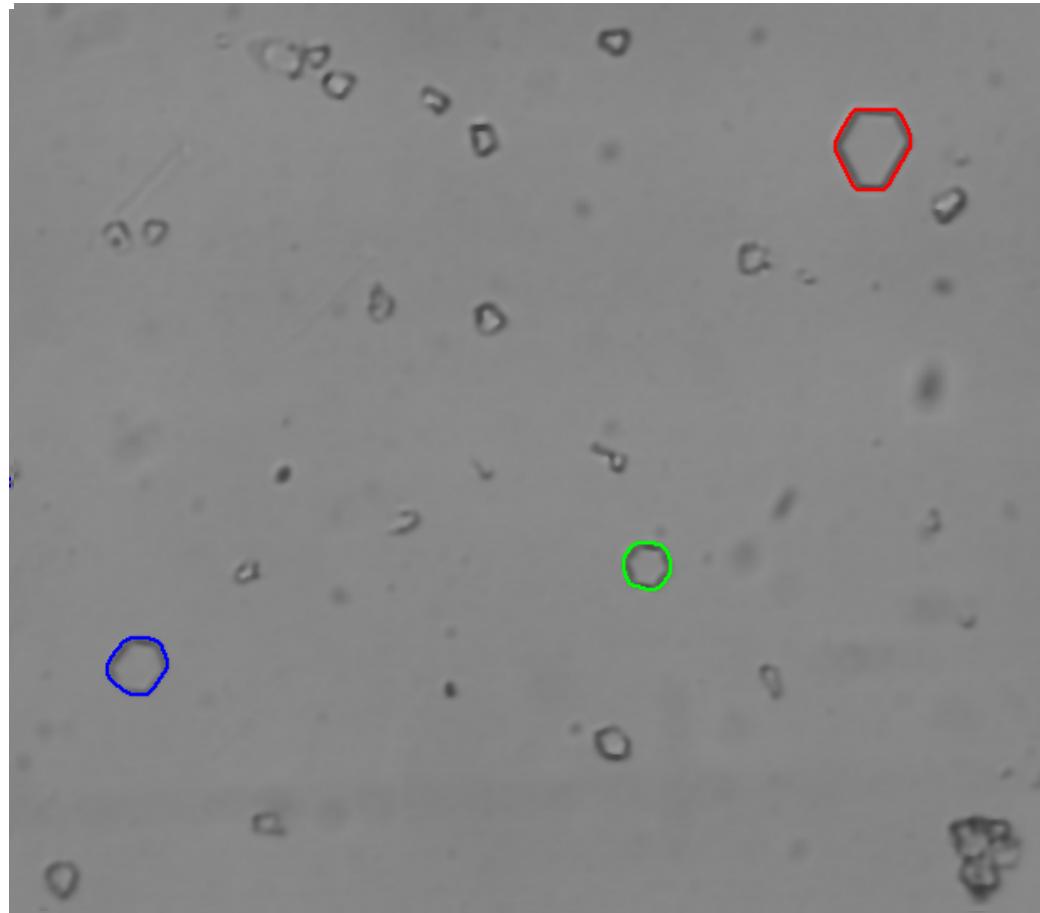
- ✓ **Area**
- ✓ Perimeter
- ✓ Convex hull
- ✓ Circularity
- ✓ Rectangularity
- ✓ Roughness/Compactness
- ✓ Width
- ✓ Height
- ✓ Length
- ✓ Principal/Secondary axis
- ✓ Principal axis angle
- ✓ Center of gravity
- ✓ ...



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Objective: locate hexagonal crystals in the image

Step 1: extract blobs without any restrictions

Step 2: filter blob with a criteria on area. Only blobs with an area in a given range are kept.

Step 3: filter blob with a criteria on entropy. Only blobs with an entropy in a given range are kept. Entropy measure consists in a statistical analysis of the gray level inside a blob.



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### EXERCISE 2

- Based on the script demo about basic computer vision

Can you describe in sub groups the main steps to program to identify cracks inside a Syringes 1,5ml filled at 0,5ml with a heavy dense suspension viscosity 1?